

Sense Me without Knowing Me!

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A Joint Work with:

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Context

1973 ■ Location (~50m) Microphone

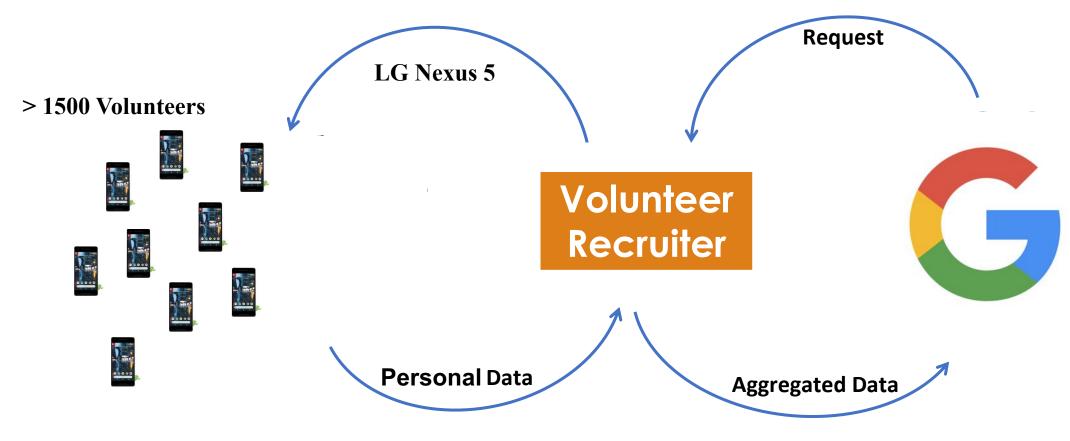
2018

- ► Location (~3m)
- Microphone
- Gyroscope
- Accelerometer
- Barometer
- Magnetometer
- Thermometer
- Proximity
- Ambient Light
- Humidity



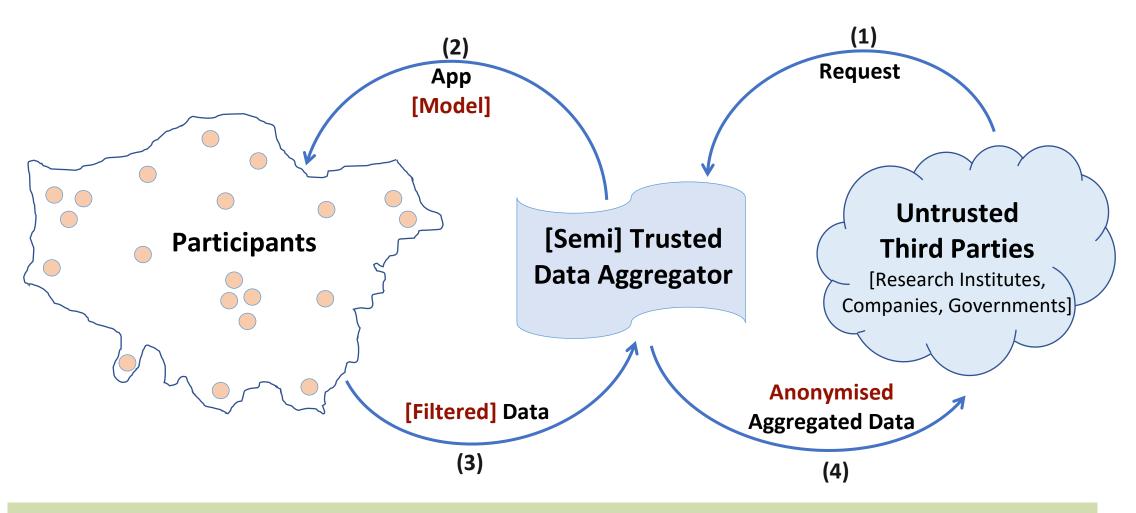
Smart devices measure more and more data every generation.

An Example Google ATAP project Abacus



Goal: using biometric patterns, like motion, instead of password

Context



Privacy-Preserving Sensing

MotionSense Dataset

- ☐ Same Activity Set: 6 ADL activities
- ☐ Same Place
- ☐ Same Phone in the Front Pocket
- □ Accelerometer and Gyroscope

24 Different Subjects:

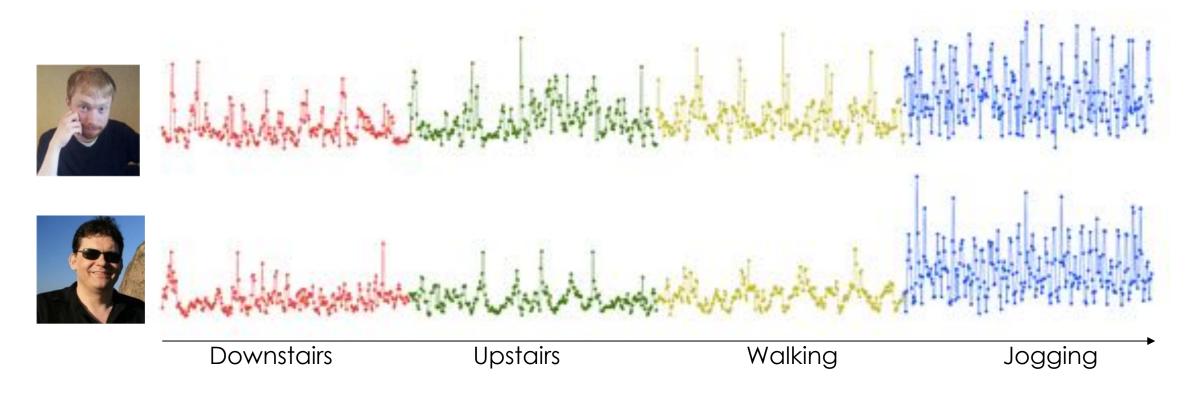
- Gender: 14 male 10 female
- Age: [18 40] years old
- **Weight:** [45,105] kg
- **Height:** [160, 195] cm







MotionSense Dataset



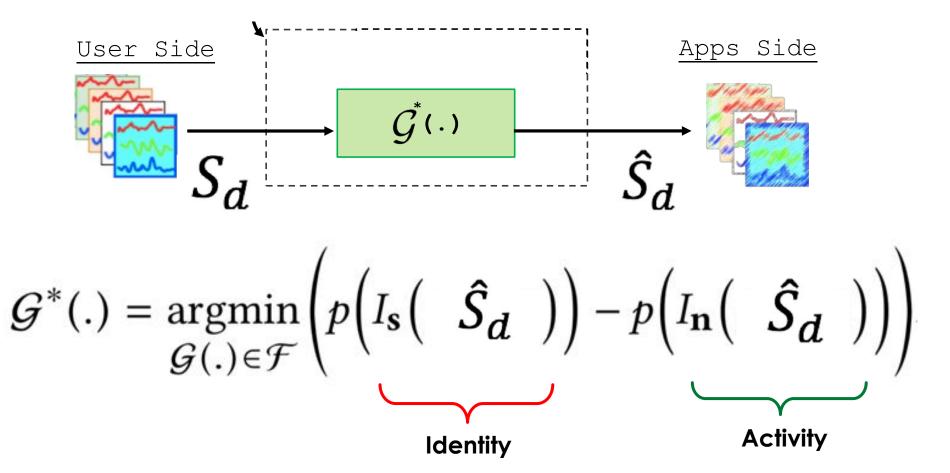
Accelerometer_(magnitude) Data

Some Results

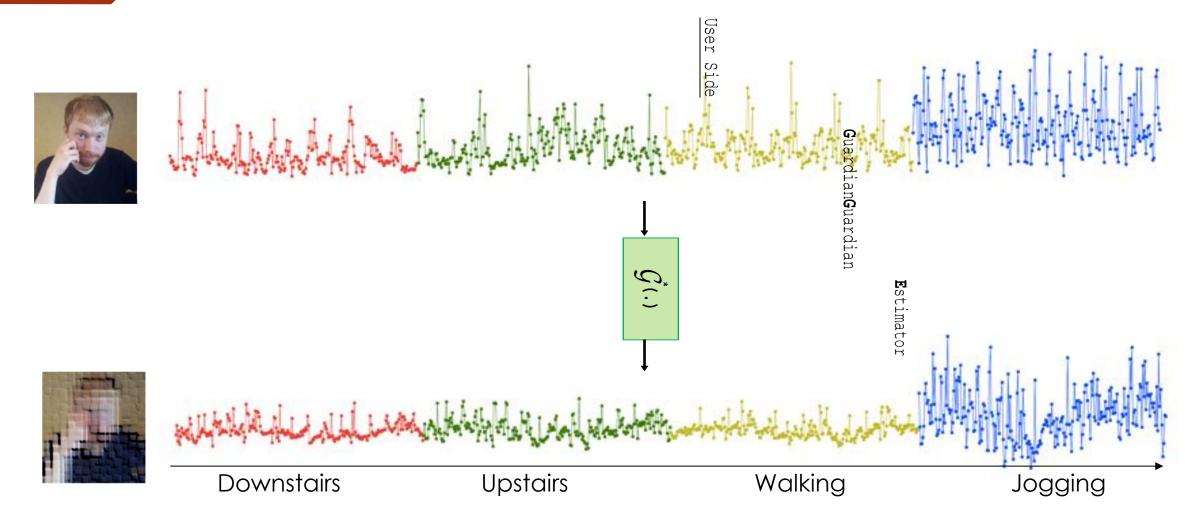
- 1-D Accelerometer_{(magnitude):} (50Hz)
 Time-Window 5 second
- Deep Convolutional Network

	Classification Accuracy	
activity	~ 98%	
gender	~ 96% ~ 89%	
Identity		

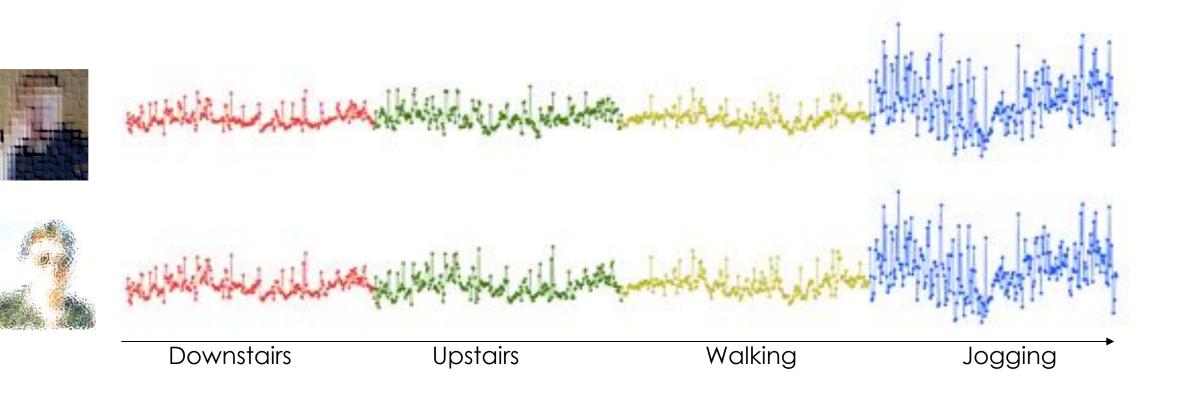
Sensor Data Anonymisation



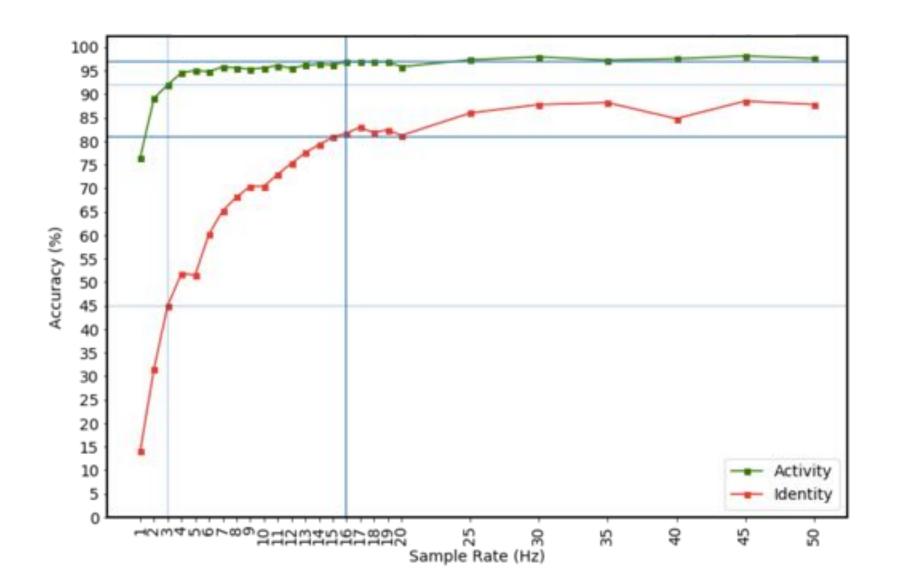
After Transformation



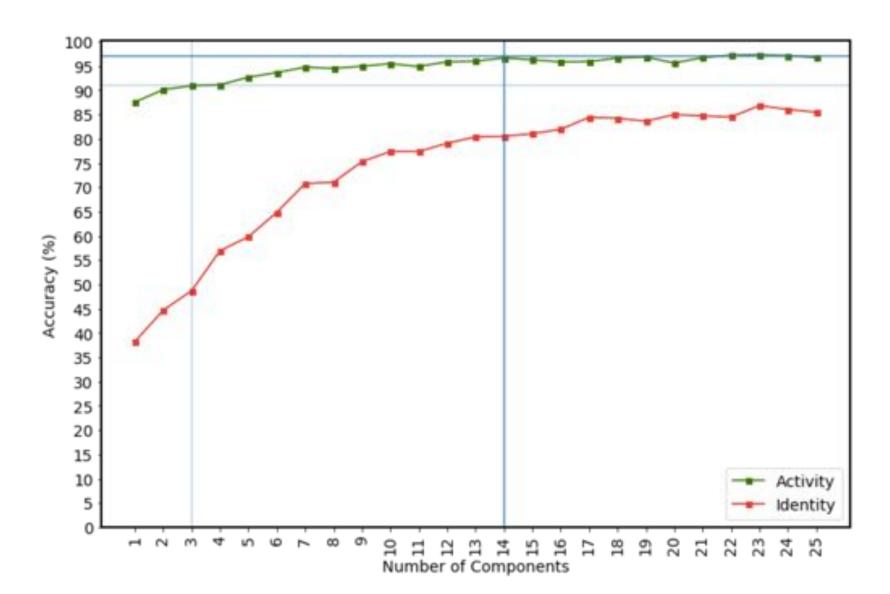
Transformed Data



G0: Downsampling

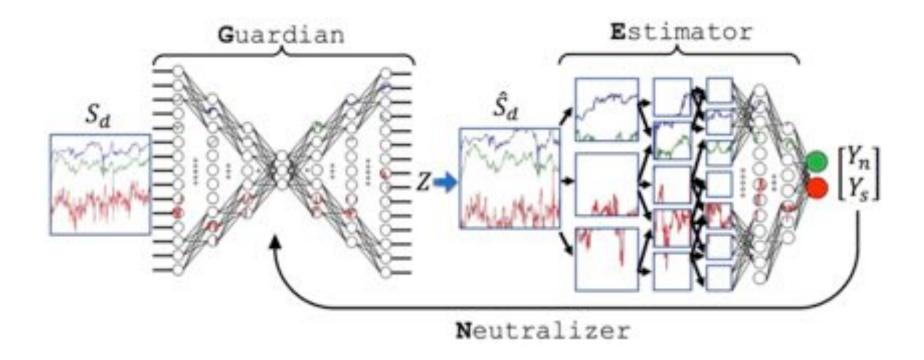


G1: Singular Spectrum Analysis



G*: Feature-Based Reconstruction

- I. Encode original data into the feature set.
- II. Decode based on features corresponding to non-sensitive task.



Comparing the Tradeoffs

	Original	G*: FBR	G1: SSA (14 Components)	G0: DownSampling (16 Hz)
Activity	~ 98	~ 92	~ 92	~ 92
Identity	~ 89	~ 18	~ 60	~ 55

 \triangleright The accuracy(%) on validation data during the training process

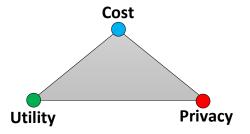
Related Work:

> [Xiao et al. 2018] : mutual information based feature selection and sampling rate adjustment

	Original	Best Sub Set of Feature	s Most Private One
Activity	~ 95	~ 95	~ 70
Identity	~ 95	~ 33	~ 16

Next Steps

- Practical:
 - The **Cost** of the solution on **Edge** devices?



- Theoretical:
 - Provide a statistical guarantee (probabilistic bound)
 - o Differential Privacy: Composition Theorem?
 - Mutual Information : Joint Distributions?

Thanks!

Link to the Dataset and Paper's Repository: bit.ly/eli-dw18







